

Precision Positioning Systems: Dynamics and Control

Overview

Precision positioning systems design deals with the design of controlled motion systems by the integration of functional elements from a multitude of disciplines. It starts with thinking how the required function can be realised by the combination of different subsystems according to a Systems Engineering approach (V-model).

It should be noted that the control principles used in this course place a strong emphasis on frequency domain methods by linearising the system at its working point with the use of Bode and Nyquist plots. The main reason for this emphasis is the strong focus in other control related courses on (non-linear) time domain related methods while linearised frequency domain related methods are still dominantly applied in the industry.

Modules	<p>The course covers the following two main subjects:</p> <p>A: Dynamics of motion systems in the time and frequency domain, including analytical frequency transfer functions that are represented in Bode and Nyquist plots.</p> <p>B: Motion control in the frequency domain with PID and advanced fractional order PID-feedback and model-based feedforward control-principles that effectively deal with the mechanical dynamic anomalies (resonances and eigenmodes) of the plant.</p> <p>Number of participants for the course will be limited to 50</p>	<p>8 – 12 Feb, 2021</p>
Who Should Attend	<ul style="list-style-type: none"> ▪ Faculty and Students at all levels (BTech/MSc/MTech/PhD) from reputed technical/academic institutions. ▪ Executives, engineers, Scientists, and researchers from manufacturing, service and government organizations including R&D laboratories. 	
Fees	<p>The participation fees for taking the course is as follows:</p> <p>Participants from abroad : US \$500</p> <p>Industry/ Research Organizations: INR 5000</p> <p>Faculty Members: INR 2000</p> <p>Students/Research Scholars: INR 1000</p> <p>The above fee includes all instructional materials, computer use for tutorials and assignments, laboratory equipment usage charges, 24 hr free internet facility. The participants will be provided with accommodation on payment basis.</p>	

The Faculty



Hassan HosseinNia received his PhD degree with honors "cum laude" in Electrical Engineering specializing in automatic control: application in mechatronics, from the University of Extremadura, Spain in 2013. His main research interests are in precision mechatronic system design, precision motion control and mechatronic system with distributed actuation and sensing. He has an industrial background working at ABB, Sweden. Since October 2014 he is appointed as an Assistant Professor at the Department of Precision and Microsystems Engineering at TU Delft, The Netherlands. He is an Associate Editor of the International Journal of Advanced Robotic Systems since 2017. He is general chair of 7th international conference in control, mechatronics and automation. He is a senior member of IEEE since 2018.



Sathans received his PhD degree in the area of intelligent control and its applications to power systems from the National Institute of Technology Kurukshetra, Haryana, India, in 2012 where, he is currently serving as Professor in the Department of Electrical Engineering. His research interests include intelligent control techniques, control issues in hybrid energy systems, evolutionary algorithms and their applications in power systems.



Amit Kumar received his PhD degree in the area of load frequency control and modern heuristic optimization techniques in hybrid power system from the National Institute of Technology Kurukshetra, Haryana, India, in 2018 where he is currently serving as Assistant Professor in the Department of Electrical Engineering. His research interests include bio-inspired computing methods, evolutionary optimization algorithms etc. and their applications in power system.

Course Coordinators

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